Please amend the claims as follows:

Listing of Claims:

Claim 1 (Currently Amended): A system for estimating quantities of pollutant

compounds emitted in the exhaust gases of a diesel engine of a motor vehicle, comprising

means for regenerating a solid particulate filter, an electronic control unit for managing the

engine operation comprising data memories, characterized in that it comprises and further

comprising:

[[-]] one or more neural networks (1);

[[-]] input data (2) representative of the engine operation and, optionally, of the

vehicle movement, said data (2) being available in the electronic control unit for managing

the engine operation without adding a sensor; and

[[-]] means (4) for cumulating the estimated quantities (3).

Claim 2 (Currently Amended): The system as claimed in claim 1, characterized in

that it comprises comprising 10 to 15 neurons.

Claim 3 (Currently Amended): The system as claimed in either of claims 1 and 2,

characterized in that it comprises further comprising training databases of the neural network,

or networks (1) said databases being vehicle drive sequences of at least a few minutes.

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Claim 4 (Currently Amended): The system as claimed in any one of claims 1 to 3 characterized in that claim 1, wherein the data used at the input of the neural network or networks (1) comprise at least one of the following parameters:

- [[-]] the engine speed (7) at two consecutive times t and t- Δt ;
- [[-]] the fuel flow rate (8) at three consecutive times t, t- Δ t and t- 2Δ t;
- [[-]] the engine coolant (9) temperature; and
- [[-]] the vehicle speed (10) at time t;

where Δt is the preset time interval between two consecutive measurement times and eharacterized in that it comprises further comprising means for estimating at least the cumulative quantity (16) of the soot in the exhaust gases which will be retained by the particulate filter.

Claim 5 (Currently Amended): The system as claimed in any one of claims 1-4, characterized in that claim 1, wherein the data used at the input of the neural network or networks (1) comprise at least one of the following parameters:

- [[-]] the engine speed (7) at two consecutive times t and t- Δt ;
- [[-]] the fuel flow rate (8) at three consecutive times t, t- Δ t and t- 2Δ t;
- [[-]] the engine coolant (9) temperature; and
- [[-]] the fuel-air ratio (18) of the mixture at time t;

where Δt is the preset time interval between two consecutive measurement times and eharacterized in that it comprises further comprising means (15) for estimating at least the cumulative quantity (16) of the soot in the exhaust gases which will be retained by a particulate filter.

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Claim 6 (Currently Amended): The system as claimed in any one of claims 1 to 5 claim 1, adapted to an engine with common rail injection, characterized in that wherein the data used at the input of the neural network or networks (1) at time t comprise at least one of the following parameters:

- [[-]] the fuel preinjection rate (19) in the engine;
- [[-]] the main (2) fuel injection rate in the engine;
- [[-]] the relative displacement (21) of a piston with respect to top dead center from the time when the last fuel injection in the piston cylinder started;
- [[-]] the relative displacement (22) of a piston with respect to top dead center from the time when the last main fuel injection in the piston cylinder started;
 - [[-]] the engine coolant temperature (9);
 - [[-]] the engine air feed rate (23);
 - [[-]] the pressure (24) inside the common rail; and
 - [[-]] the engine speed (7);

and in that wherein the estimated quantities of pollutant compounds comprise at least one of the following quantities:

- [[-]] the cumulative quantity (16) of the soot in the exhaust gases that will be retained by a particulate filter;
 - [[-]] the cumulative quantity (35) of nitrogen oxides in the exhaust gases;
 - [[-]] the cumulative quantity (31) of the carbon oxides in the exhaust gases; and
 - [[-]] the cumulative quantity (27) of hydrocarbons in the exhaust gases.

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Claim 7 (Currently Amended): The system as claimed in any one of claims 1 to 6,

eharacterized in that claim 1, wherein no output (3,5) from the system is looped to an input

(2) of the system to avoid any problem of stability.

Claim 8 (Currently Amended): The system as claimed in any one of claims 1 to 7,

characterized in that it comprises claim 1, further comprising means for resetting the

estimated quantities of particulates, independently of each other.

Claim 9 (Currently Amended): A method for evaluating a system implementing any

one of claims 1 to 8, characterized in that it evaluates of claim 1, said method comprising the

step of evaluating the best configuration of the neural network or networks (1) by calculating

the error on the output quantities (3) by cumulation on a sliding window.

Claim 10 (Currently Amended): The method as claimed in claim 9, characterized in

that comprising the step of determining the sliding window is determined so that its size is

minimal while allowing an estimation error lower than a preset value.

Claim 11 (Currently Amended): The method as claimed in claim 10, characterized in

that wherein the size of the window corresponding to a vehicle movement varies between 0.5

km and 1.5 km to allow an estimation error of not more than 5 g of solid particulates emitted

per 135 km traveled by the vehicle.

Claim 12 (Currently Amended): The method as claimed in any one of claims 9 to 11,

eharacterized in that claim 9, comprising the step of discarding part of the data reserved for

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training the neural network or networks (1) is discarded to perform a validation without the

data used.

Claim 13 (Currently Amended): The application of the system as defined in either of

claims 6 and 7, to control A method of controlling the means for regenerating the solid

particulate filter of either claims 6 and 7, the method comprising the step of comparing using

a comparison between the estimated quantity of cumulative soot (16) and with a memorized

threshold value.

Claim 14 (Currently Amended): The application of the system as defined in claim 8,

to aid the calibration of A method of calibrating engine control strategies from the estimation

of the comprising a step of estimating engine emissions over a vehicle drive cycle, wherein

said estimating step is performed with the system as defined in claim 8.